# Computations with Low Rank Matrices in Logarithmic Space

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## Outline



#### Introduction

- Low Rank Matrices
- Matrix Sampling



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Applications







#### Introduction

Low Rank Matrices

Matrix Sampling

2 Space Bounded Algorithms
 • Reducing Randomness
 • Applications



# Why low rank matrices?

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#### • Example: recommendation systems



Source: Google C<sup>\*</sup> developers.google.com/machine-learning/ recommendation/collaborative/matrix



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- The σ<sub>i</sub>(M)'s are called the singular values of M and the columns of U and V are called the left and right singular vectors of M.



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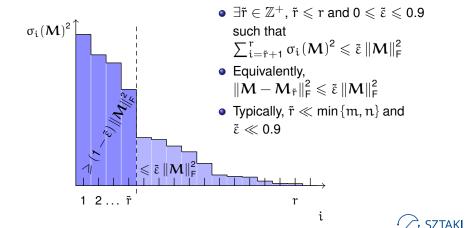
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# Approximately low rank matrices

If M can be approximated well by a low rank matrix then its singular values look like this.







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Space Bounded Algorithms

## Variance



### Variance

$$\operatorname{Var}(\mathbf{c}\mathbf{c}^{\mathsf{T}}) \stackrel{\mathsf{def}}{=} \mathbb{E}\left[\left\|\mathbf{c}\mathbf{c}^{\mathsf{T}} - \mathbf{M}\mathbf{M}^{\mathsf{T}}\right\|_{\mathsf{F}}^{2}\right]$$



### Variance

$$\begin{aligned} \text{Var}\left(\textbf{c}\,\textbf{c}^{\mathsf{T}}\right) &\stackrel{\text{def}}{=} \mathbb{E}\left[\left\|\textbf{c}\,\textbf{c}^{\mathsf{T}} - \textbf{M}\textbf{M}^{\mathsf{T}}\right\|_{\mathsf{F}}^{2}\right] \\ &= \sum_{\mathfrak{i}, \mathfrak{j} \in [\mathfrak{m}]} \text{Var}\left(\left(\textbf{c}\,\textbf{c}^{\mathsf{T}}\right)(\mathfrak{i}, \mathfrak{j})\right) \end{aligned}$$



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## Variance cont.

$$\mathbb{E}\left[\left\|\mathbf{c}\mathbf{c}^{\mathsf{T}}-\mathbf{M}\mathbf{M}^{\mathsf{T}}\right\|_{\mathsf{F}}^{2}\right] \leqslant \mathbb{E}\left[\sum_{\mathfrak{i},\mathfrak{j}\in[m]}\frac{\mathbf{M}(\mathfrak{i},\mathfrak{J})^{2}\,\mathbf{M}(\mathfrak{j},\mathfrak{J})^{2}\,\|\mathbf{M}\|_{\mathsf{F}}^{4}}{\|\mathbf{M}(\mathfrak{i},\mathfrak{J})\|^{4}}\right]$$



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#### Why does M have to be low rank?

We have the following bound: 
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- Left hand side:  $\|\mathbf{M}\mathbf{M}^{\mathsf{T}}\|_{\mathsf{F}}^{2} = \sum_{k=1}^{r} \sigma_{\mathbf{M}}(k)^{4}$ • Right hand side:  $\frac{1}{s} \left(\sum_{k=1}^{r} \sigma_{\mathbf{M}}(k)^{2}\right)^{2}$



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which holds if s > r.







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# Random walks on expander graphs

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  - We need: good expanders exist for all  $N = n^4$ .



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• Let  $\nu_1,\nu_2,\ldots,\nu_s$  be the vertices visited by the walk. Then

$$C = \frac{1}{\sqrt{s}} \begin{bmatrix} \frac{M(:,f(\nu_1))}{\sqrt{p_{f(\nu_1)}}} & \frac{M(:,f(\nu_2))}{\sqrt{p_{f(\nu_2)}}} & \cdots & \frac{M(:,f(\nu_s))}{\sqrt{p_{f(\nu_s)}}} \end{bmatrix}$$



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• Randomness required: O(log(n) + s).



# Approximation with expanders

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For  $M \in \mathbb{R}^{m \times n}$ , let  $C \in \mathbb{R}^{m \times s}$  be the matrix we get by the sampling procedure. It holds that

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This procedure uses O(s + log(mn)) space including the number of random bits.

- The constant in the big O notation only depends on the expansion parameter of the graph.
- Only the "work space" counts in the space complexity, reading the input and writing the output does not.

# Derandomized algorithm

We can iterate over all the possible random bits.



# Reducing Randomness Derandomized algorithm

We can iterate over all the possible random bits.

#### Theorem

There exists a deterministic algorithm that, on input  $M \in \mathbb{R}^{m \times n}$ , outputs  $C \in \mathbb{R}^{m \times s}$  for which

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- $\|AA^{\mathsf{T}} BB^{\mathsf{T}}\|_{\mathsf{F}}$  is a distance measure between A and B.
- For different random bits we get different CC<sup>T</sup> matrices. We just have to pick one that is close to many others.



### Outline



### Introduction

Low Rank Matrices

Matrix Sampling



Applications



## Low rank approximation with singular vectors

### Theorem (known from earlier)

For any  $\mathbf{A} \in \mathbb{R}^{m \times s}$ ,  $\mathbf{M} \in \mathbb{R}^{m \times n}$ ,  $k \ge 1$ , if the columns of  $\mathbf{U}_k \in \mathbb{R}^{m \times k}$  are the left singular vectors corresponding to the top k singular values of  $\mathbf{A}$  and  $\mathbf{M}_k$  is the best rank-k approximation to  $\mathbf{M}$  then

$$\left\|\mathbf{M} - \mathbf{U}_{k}\mathbf{U}_{k}^{\mathsf{T}}\mathbf{M}\right\|_{\mathsf{F}}^{2} \leqslant \left\|\mathbf{M} - \mathbf{M}_{k}\right\|_{\mathsf{F}}^{2} + 2\sqrt{k}\left\|\mathbf{A}\mathbf{A}^{\mathsf{T}} - \mathbf{M}\mathbf{M}^{\mathsf{T}}\right\|_{\mathsf{F}}.$$



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- The first term is the best possible error.
- The second term is what we pay for calculating with A.



### Low rank approximation in small space

# Problem with the previous theorem (substituting C for A): calculating SVD of C is costly



### Low rank approximation in small space



### Low rank approximation in small space

Problem with the previous theorem (substituting C for A): calculating SVD of C is costly even if we use the small matrix  $C^{\mathsf{T}}C \in \mathbb{R}^{s \times s}$ .

• Idea: Use  $CC^+$  instead of  $U_k U_k^T$ .



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  - C<sup>+</sup> is the Moore-Penrose pseudoinverse of C.
  - If the SVD of C is  $U\Sigma V^T$  then  $C^+ = V\Sigma^{-1}U^T$ .
  - So,  $\mathbf{C}\mathbf{C}^+ = \mathbf{U}\mathbf{U}^\mathsf{T} = \mathbf{U}_{\mathsf{rank}(C)}\mathbf{U}^\mathsf{T}_{\mathsf{rank}(C)}$ .
  - But calculating the Moore-Penrose pseudoinverse is easier than the SVD. It reduces to inverse calculation which can be done in small space.



# Low rank approximation in small space cont.

#### Theorem

Let the input matrix be  $\mathbf{M} \in \mathbb{R}^{m \times n}$ . Suppose that, for some  $\tilde{\mathbf{r}} \in \mathbb{Z}^+$ ,  $\tilde{\mathbf{r}} \leq \operatorname{rank}(\mathbf{M})$  and  $0 \leq \varepsilon \leq 0.9$ , it holds that  $\|\mathbf{M} - \mathbf{M}_{\tilde{\mathbf{r}}}\|_{\mathsf{F}} \leq \varepsilon \|\mathbf{M}\|_{\mathsf{F}}$  where  $\mathbf{M}_{\tilde{\mathbf{r}}}$  is the best  $\tilde{\mathbf{r}}$ -rank approximation of  $\mathbf{M}$ .



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Intuitively, C must "cover" most of the space that is spanned by the singular vectors corresponding to the top  $\tilde{r}$  singular values of M.

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Intuitively, **C** must "cover" most of the space that is spanned by the singular vectors corresponding to the top  $\tilde{r}$  singular values of **M**. Then  $CC^+$  is a projector that projects to this "covered" subspace.

- If  $\tilde{r} \ll n$  then  $O(\tilde{r} \log \tilde{r} + \log(mn))$  space is less than
  - storing  $\tilde{r}$  column indices, which would require  $\tilde{r} \cdot \log n$  space,



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- Matrix multiplication can be done in this space bound so we can also output  $CC^+M$  and  $C^+$ .



### Moore-Penrose pseudoinverse of M

We can calculate the Moore-Penrose pseudoinverse of  $\boldsymbol{M}$  if  $\boldsymbol{M}$  is low rank.



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• Bound gets worse:  $\tilde{r} \to r^2$ . This is because the sampled matrix must "cover" the whole space spanned by the singular vectors of M.



### Singular value decomposition of M

If we can store  $C^{\mathsf{T}}C$  then we can calculate an approximate SVD of M.



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The bound gets worse:  $r^2 \rightarrow r^4$ .





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# Thank you for your attention!

Got comments, questions, ideas? Email me at ⊠peresz@sztaki.hu

