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Scaling limits for
self-interacting random
walks and diffusions, (4)

Lecture notes for
Berlin-Zürich Summer
School on

Stochastic Models of
Complex processes

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The environment as seen from the moving particle, stationary picture

① Myopic Self-Avoiding walk on \mathbb{Z}^d - continuous time

② The Brownian Polymer model

① MSAW on \mathbb{Z}^d :

$X(t)$ nearest neighbour jump walk on \mathbb{Z}^d

$$l(t, x) = l(0, x) + |\{0 < s < t : X(s) = x\}|$$

$$P(X(t+dt) = y \mid \text{past}, X(t) = x) =$$

$$r(l(t, x) - l(t, y)) dt + o(dt)$$

$$r: \mathbb{R} \rightarrow (0, \infty)$$

$$\Delta(u) = r(u) + r(-u)$$

$$a(u) = r(u) - r(-u) \quad \boxed{\text{non-decreasing}}$$

Natural approach: follow the environment
(= local time field) from the position
of the random walker.

unit vector in
direction k .

$$\omega_k(x) = l(x) - l(x + e_k)$$

$$\Omega := \{ \underline{\omega} = (\omega(x))_{x \in \mathbb{Z}^d} :$$

$$\omega(x) = (\omega_1(x), \dots, \omega_d(x)) \in \mathbb{R}^d,$$

$$\left. \begin{aligned} \omega_k(x) + \omega_k(x + e_k) &= \omega_l(x) + \omega_l(x + e_l) \\ \text{gradient condition} \end{aligned} \right\}$$

$\eta(t) \in \Omega$: the environment seen from
the position of the walker: Markov pr

infinitesimal generator: later

A relevant probability measure on Ω :

$$V: \mathbb{R} \rightarrow [0, \infty) \quad V(u) := \int_0^u (r(v) - r(-v)) dv$$

$V(u) = V(-u)$, increases at least linearly at $\pm \infty$

$$\pi(d\omega) = \exp \left\{ - \sum_{x \in \mathbb{Z}^d} V(\omega_k(x)) \right\} d\omega$$

$\left\{ \omega_k(x) : x \in \mathbb{Z}^d, k=1, \dots, d \right\}$ iid $\frac{e^{-V(u)} du}{Z}$
conditioned to be gradient

Properly defined as Gibbs measures

Particular case: $r(v) - r(-v) = v$

$$V(u) = \frac{u^2}{2}$$

$\pi(d\omega) =$ gradient of massless free Gaussian field

$$E(\omega_k(x) = 0); \quad E(\omega_k(x)\omega_k(y)) = C_{kk}(y-x)$$

$$C_{kl}(z) = \frac{1}{(2\pi)^d} \int_{[-\pi, \pi]^d} \frac{(1 - e^{i\theta \cdot e_k})(1 - e^{i\theta \cdot e_l})}{D(\theta)} d\theta$$

$$D(\theta) = \frac{1}{d} \sum_{j=1}^d (1 - \cos \theta_j)$$

Remark: we don't consider now the
tilted fields.

Shifts:

$$\tau_k: \Omega \rightarrow \Omega; \quad (\tau_k(\omega))(x) = \omega(x + e_k)$$

$(\Omega, \mathcal{F}, (\tau_k)_{k=1, \dots, d})$ ergodic.

We put ourselves in $L^2(\Omega, \tau)$:

The infinitesimal generator and its adjoint:

$$(Gf)(\underline{\omega}) = \sum_{k=1}^d \left(\frac{\partial f}{\partial \omega_k(0)}(\underline{\omega}) - \frac{\partial f}{\partial \omega_k(-e_k)}(\underline{\omega}) \right)$$

$$+ \sum_{k=1}^d \left\{ r(\omega_k(0)) (f(\tau_k \underline{\omega}) - f(\underline{\omega})) + \right.$$

$$\left. r(-\omega_k(-e_k)) (f(\tau_k^{-1} \underline{\omega}) - f(\underline{\omega})) \right\}.$$

$$(G^*f)(\underline{\omega}) = \sum_{k=1}^d \left(-\frac{\partial f}{\partial \omega_k(0)}(\underline{\omega}) + \frac{\partial f}{\partial \omega_k(-e_k)}(\underline{\omega}) \right)$$

$$+ \sum_{k=1}^d \left\{ r(-\omega_k(0)) (f(\tau_k \underline{\omega}) - f(\underline{\omega})) + \right.$$

$$\left. r(\omega_k(-e_k)) (f(\tau_k^{-1} \underline{\omega}) - f(\underline{\omega})) \right\}$$

Computation of the adjoint follows from the integration by parts formula:

$$\left(\frac{\partial}{\partial \omega_k(x)} \right)^* = - \frac{\partial}{\partial \omega_k(x)} + \left(r(\omega_k(x)) - r(-\omega_k(x)) \right).$$

First consequences:

① π is stationary & ergodic measure for the Markov process $\eta(t)$

② Yaglom (skew) reversibility:

$$(Jf)(\underline{\omega}) := f(-\underline{\omega})$$

$$J = J^* = J^{-1}$$

$$G^* = JGJ$$

Probabilistic meaning: $\eta_{(t)}^* := -\eta(t)$

then $\eta^*(t)$ law $\eta(t)$.

The displacement:

$$X(t) - X(s) = M(t) - M(s) + \int_s^t \varphi(\gamma(u)) du$$

where $\varphi: \Omega \rightarrow \mathbb{R}^d$

$$\begin{aligned} \varphi_k(\underline{\omega}) &:= r(\omega_k(0)) - r(-\omega_k(-e_k)) \\ &= \left(s(\omega_k(0)) - s(\omega_k(-e_k)) \right) + \\ &\quad \left(a(\omega_k(0)) + a(\omega_k(-e_k)) \right) \\ &= \overline{\varphi}_k(\underline{\omega}) + \tilde{\varphi}_k(\underline{\omega}) \end{aligned}$$

$$\begin{aligned} X(t) - X(s) &= M(t) - M(s) \\ &\quad + \int_s^t \overline{\varphi}(\gamma(u)) du \\ &\quad + \int_s^t \tilde{\varphi}(\gamma(u)) du \end{aligned} \left. \begin{array}{l} \text{Martingale with} \\ \text{stationary \& ergodic} \\ \text{increments} \\ \text{to be treated} \\ \text{by martingale} \\ \text{approximation} \\ \text{à la Kipnis Varadhan} \end{array} \right\}$$

② The Brownian Polymer model

History: Norris-Rogers-Williams '87

Durrett-Rogers '92

Crawston-LeJan '95

Crawston-Mountford '96

Mountford-Tarrès '08. ...

$$t \mapsto X(t) \in \mathbb{R}^d$$

$$X(t) = \sigma B(t) + \int_0^t \int_0^s F(X(s) - X(u)) du ds$$

$$F(x) = -\text{grad } V(x)$$

$$V(x) = \exp \left\{ -|x|^2/2 \right\} \text{ or "something else of this kind"}$$

Remark: qualitatively other choices of $F(\cdot)$ are also possible — but this one is the most interesting ...

$$dX(t) = \sigma dB(t) + \left\{ \int_0^t F(X(t) - X(u)) du \right\} dt$$

Let $L(t, dx)$ be the occupation time measure of $X(\cdot)_t$

$$L(t, A) = \int_0^t \mathbb{1}(X(u) \in A) du$$

then

$$dX(t) = \sigma dB(t) - \int_{\mathbb{R}^d} F(z) L(t, X(t) + dz) dt$$

$$dX(t) = \sigma dB(t) - \text{grad}(V * L(t, \cdot))(X(t)) dt$$

This is the same mechanism in continuous space ~~time~~ as MSAW

on \mathbb{R}^d .

In 1d compare also with TSM

The environment as seen from the position
of the moving particle:

1st step separate the evolution of the
environment

$$\xi(t, \cdot) : \mathbb{R}^d \rightarrow \mathbb{R}^d$$

$$\begin{cases} \xi(t, x) = \boxed{\xi(0, x)} + \int_0^t F(x - X(u)) du \\ X(t) = X(0) + \sigma(B(t) - B(0)) + \int_0^t \xi(s, X(s)) ds \end{cases}$$

Then:

$$X(t) = X(0) + \sigma(B(t) - B(0)) +$$

$$\int_0^t \left\{ \boxed{\xi(0, X(s))} + \int_0^s F(X(s) - X(u)) du \right\} ds$$

we allow initial value for the
field ξ .

2nd step

Travel with the moving particle

$$\eta(t, \cdot) : \mathbb{R}^d \rightarrow \mathbb{R}^d$$

$$\eta(t, x) := \xi(t, X(t) + x)$$

Then $t \mapsto \eta(t, \cdot)$ will be a Markov process on its own, in some function space Ω .

Next: we identify a pretty stationary (and ergodic) measure for $\eta(t, \cdot)$:

Ansatz: zero mean, translation-invariant Gaussian with covariances

$$\mathbb{E}(\eta_k(t, x) \eta_l(t, y)) = C_{kl}(y-x)$$

Mind: same t . $t \mapsto \eta(t)$ is not a Gaussian process.

Moment generating functional:

$u: \mathbb{R}^d \rightarrow \mathbb{R}^d$ test function

$$\phi(t, u) := \mathbb{E}(\exp\{\langle u, \eta(t) \rangle\})$$

Notation:

$$\langle u, v \rangle = \langle u_k, v_k \rangle = \int_{\mathbb{R}^d} u_k(x) v_k(x) dx$$

[with summation over repeated subscripts

Goal: Find condition on $C_{kl}(z)$

for $\partial_t \phi(t, u) \equiv 0$.

Itô:

$$d \langle u_k, \eta_k(t) \rangle = -\sigma \langle \partial_\ell u_k, \eta_k(t) \rangle dB_\ell(t) + \left(\frac{\sigma^2}{2} \langle \partial_{\ell\ell}^2 u_k, \eta_k(t) \rangle - \langle \partial_\ell u_k, \eta_k(t) \rangle \eta_\ell(t, 0) + \langle \partial_\ell u_k, V \rangle \right) dt$$

Hence:

$$\mathbb{E} \left(d \exp \langle u_k, \eta_k(t) \rangle \middle| \mathcal{F}_t \right) = \exp \langle u_k, \eta_k(t) \rangle \cdot$$

$$\left(\frac{\sigma^2}{2} \langle \partial_{\ell\ell}^2 u_k, \eta_k(t) \rangle + \frac{\sigma^2}{2} \langle \partial_\ell u_k, \eta_k(t) \rangle \langle \partial_\ell u_m, \eta_m(t) \rangle - \langle \partial_\ell u_k, \eta_k(t) \rangle \eta_\ell(t, 0) + \langle \partial_\ell u_k, V \rangle \right) dt$$

Use now the Gaussian Ansatz.

If (X, Y, Z) are jointly Gaussian, zero mean, then:

$$\mathbb{E}(Y e^X) = \exp \{ \mathbb{E} X^2 / 2 \} \mathbb{E}(XY)$$

$$\mathbb{E}(YZ e^X) = \exp \{ \mathbb{E} X^2 / 2 \} \left(\mathbb{E}(YZ) + \mathbb{E}(XY) \mathbb{E}(XZ) \right)$$

Hence:

$$\exp\{-\langle U_k, C_{kl} * U_l \rangle\} E\left(\frac{d}{dt} \exp\{\langle U_k, \eta_k(t) \rangle\}\right) / dt =$$

$$\frac{\delta^2}{2} \langle \partial_{ll}^2 U_k, C_{km} * U_m \rangle + \frac{\delta^2}{2} \langle \partial_l U_k, C_{km} * \partial_l U_m \rangle$$

Cancel by integr. by parts

$$+ \frac{\delta^2}{2} \langle \partial_l U_k, C_{km} * U_m \rangle \langle \partial_l U_i, C_{ij} * U_j \rangle$$

= 0

$$- \langle \partial_l U_k, C_{km} * U_m \rangle \langle U_i, C_{il} \rangle$$

$$+ \langle \partial_k U_k, V \rangle - \langle \partial_l U_k, C_{kl} \rangle$$

Condition looked after

$$\partial_l C_{kl} = \partial_k V$$

or

$$C_{kl} = \partial_{kl}^2 \Delta^{-1} V$$

$$\hat{C}_{kl}(p) = \frac{A_k p_l}{p^2} \hat{V}(p)$$

$$\Omega := \left\{ \omega \in C^\infty(\mathbb{R}^d \rightarrow \mathbb{R}^d) : \omega \text{ gradient}, \|\omega\|_{k,m,l} < \infty \right\}$$

$$\|\omega\|_{k,m,l} := \sup_{x \in \mathbb{R}^d} (1+|x|)^{-1/l} \left| \partial_{m_1, \dots, m_d} \omega_k(x) \right|$$

$$l \geq 1; k \in \{1, \dots, d\}; m = (m_1, \dots, m_d), m_j \geq 0.$$

$\pi(d\omega)$ the Gaussian measure with

$$\int_{\Omega} \omega_k(x) \pi(d\omega) = 0; \int_{\Omega} \omega_k(x) \omega_l(y) \pi(d\omega) = C_{kl}(y-x)$$

Spatial translations

$$\tau_z: \Omega \rightarrow \Omega; (\tau_z \omega)_k(x) := \omega_k(z+x)$$

$(\Omega, \pi, \tau_z: z \in \mathbb{R}^d)$ ergodic.

$L^2(\Omega, \pi) =: \mathcal{H}$ Gaussian Hilbert space

Hilbert spaces & operators:

Notation:

$\mathcal{S} = \mathcal{S}(\mathbb{R}^d \rightarrow \mathbb{R})$ Schwartz space

$\hat{\mathcal{S}} = \{ \hat{u} \in \mathcal{S}(\mathbb{R}^d \rightarrow \mathbb{C}), \overline{\hat{u}(p)} = \hat{u}(-p) \}$

Fourier transform:

$\hat{u}(p) = (2\pi)^{-d/2} \int_{\mathbb{R}^d} e^{ip \cdot x} u(x) dx$

$\check{v}(x) = (2\pi)^{-d/2} \int_{\mathbb{R}^d} e^{-ip \cdot x} v(p) dp$

$\mathcal{S}_1 := \{ u : \{1, \dots, d\} \times \mathbb{R}^d \rightarrow \mathbb{R} : u_k \in \mathcal{S} \}$

$\hat{\mathcal{S}}_1 := \{ \hat{u} : \{1, \dots, d\} \times \mathbb{R}^d \rightarrow \mathbb{C} : \hat{u}_k \in \hat{\mathcal{S}} \}$

$\langle u, v \rangle := \iint_{\mathbb{R}^d \times \mathbb{R}^d} u_k(x) \hat{C}_{kl}(y-x) v_l(y) dx dy$

$\langle \hat{u}, \hat{v} \rangle := \int_{\mathbb{R}^d} \hat{u}_k(p) \hat{C}_{kl}(p) \hat{u}_l(-p) dp$

Basic Hilbert space:

$$V := \overline{\left\{ u \in \mathcal{F}_1 : \|u\|^2 := \langle u, u \rangle \right\}}$$

$$\hat{V} := \overline{\left\{ \hat{u} \in \hat{\mathcal{F}}_1 : \|\hat{u}\|^2 := \langle \hat{u}, \hat{u} \rangle \right\}}$$

identified by Fourier tr.

Still notation:

$$n \geq 1, \quad \underline{k} = (k_1, \dots, k_n), \quad k_j \in \{1, \dots, d\}$$

$$\underline{x} = (x_1, \dots, x_n), \quad x_j \in \mathbb{R}^d$$

$$\mathcal{F}_n := \left\{ u : \{1, \dots, d\}^n \times \mathbb{R}^{dn} \rightarrow \mathbb{R} : u_{\underline{k}} \in \mathcal{S}(\mathbb{R}^{dn} \rightarrow \mathbb{R}); \right.$$

$$\left. u_{\pi \underline{k}}(\pi \underline{x}) = u_{\underline{k}}(\underline{x}), \quad \pi \in \text{Perm}(n) \right\}$$

$$\hat{\mathcal{F}}_n := \left\{ \hat{u} : \{1, \dots, d\}^n \times \mathbb{R}^{dn} \rightarrow \mathbb{C} : \hat{u}_{\underline{k}} \in \mathcal{S}(\mathbb{R}^{dn} \rightarrow \mathbb{C}), \overline{\hat{u}_{\underline{k}}(p)} = \hat{u}_{\underline{k}}(-p), \right.$$

$$\left. \hat{u}_{\pi \underline{k}}(\pi \underline{x}) = \hat{u}_{\underline{k}}(\underline{x}); \quad \pi \in \text{Perm}(n) \right\}$$

$$\langle u, v \rangle := \sum_{\underline{k}} \sum_{\underline{l}} \iint_{\mathbb{R}^{dn} \times \mathbb{R}^{dn}} u_{\underline{k}}(x) C_{\underline{k}\underline{l}}(\gamma-x) v_{\underline{l}}(\gamma) dx d\gamma$$

$$\langle \hat{u}, \hat{v} \rangle := \sum_{\underline{k}} \sum_{\underline{l}} \int_{\mathbb{R}^{dn}} \hat{u}_{\underline{k}}(\varphi) \hat{C}_{\underline{k}\underline{l}}(\varphi) \hat{v}_{\underline{l}}(-\varphi) d\varphi$$

$$C_{\underline{k}\underline{l}}(\gamma-x) := \prod_{m=1}^n C_{k_m l_m}(\gamma_m - x_m)$$

$$\hat{C}_{\underline{k}\underline{l}}(\varphi) := \prod_{m=1}^n \hat{C}_{k_m l_m}(\varphi_m)$$

$$\mathcal{K}_n := \overline{\{u \in \mathcal{I}_n : \|u\|^2 = \langle u, u \rangle\}}$$

$$\hat{\mathcal{K}}_n := \overline{\{\hat{u} \in \hat{\mathcal{I}}_n : \|\hat{u}\|^2 = \langle \hat{u}, \hat{u} \rangle\}}$$

identified by Fourier tr

$$\mathcal{K}_n = \text{Symm}(\mathcal{V}^{\otimes n}); \quad \hat{\mathcal{K}}_n = \text{Symm}(\hat{\mathcal{V}}^{\otimes n})$$

$$\mathcal{K} := \overline{\bigoplus_{n=0}^{\infty} \mathcal{K}_n}; \quad \hat{\mathcal{K}} := \overline{\bigoplus_{n=1}^{\infty} \hat{\mathcal{K}}_n} \quad \text{Fock spaces}$$

Back to $L^2(\Omega, \mu) =: \mathcal{H}$

$$\Phi_n: \mathcal{K}_n \rightarrow \mathcal{H}$$

$$\Phi_n(u) := \frac{1}{n!} \sum_{\underline{k}} \int_{\mathbb{R}^{dn}} \mu_{\underline{k}}(x) : W_{k_1}(x_1) \cdots W_{k_n}(x_n) : dx$$

Wick product.

↑
isometry: $\|\Phi_n(u)\|_{\mathcal{H}} = \|u\|_{\mathcal{K}}$

$$\mathcal{H}_n := \text{Ran } \Phi_n = \{ \Phi_n(u) : u \in \mathcal{K}_n \}$$

Fact $\mathcal{H} = \overline{\bigoplus_{n=0}^{\infty} \mathcal{H}_n}$

$$\bigoplus_{n=0}^{\infty} \mathcal{H}_n \quad \xlongequal{\quad} \quad \bigoplus_{n=0}^{\infty} \mathcal{K}_n \quad \xlongequal{\quad} \quad \bigoplus_{n=0}^{\infty} \widehat{\mathcal{K}}_n$$

identified
by Φ_n

identified
by Fourier

we will move freely between these spaces.

Stieltjes notation

$$\phi: \mathcal{V} \rightarrow \mathcal{H}_1; \quad \phi(v) = \int_{\mathbb{R}^d} v_k(x) \omega_k(x) dx$$

$$v_1, v_2, \dots, v_n \in \mathcal{V} \quad (v_m = (v_{mk})_{k=1, \dots, d})$$

$$: \phi(v_1) \dots \phi(v_n) :$$

$$= \sum_k \int_{\mathbb{R}^{dn}} v_{1k_1}(x_1) \dots v_{nk_n}(x_n) : \omega_{k_1}(x_1) \dots \omega_{k_n}(x_n) : dx$$

Operators on \mathcal{H} — generalities:

$$A: \mathcal{V} \rightarrow \mathcal{V} \quad \text{linear operator over } \mathcal{V}$$

[linear operator \Rightarrow densely defined & closed]

$$d\Gamma(A): \mathcal{H}_n \rightarrow \mathcal{H}_n \quad \text{lin. op. over } \mathcal{H}$$

$$d\Gamma(A): \phi(v_1) \dots \phi(v_n) :$$

$$= \sum_{m=1}^n : \phi(v_1) \dots \phi(Av_m) \dots \phi(v_n) :$$

multiplication op:

$$u \in \mathcal{V}; \quad (m(u)f)(\omega) := \phi(u)(\omega) f(\omega)$$

directional differentiation:

$$v \in \Omega$$

$$\frac{\delta}{\delta v} f(\omega) := \lim_{\varepsilon \downarrow 0} \varepsilon^{-1} (f(\omega + \varepsilon v) - f(\omega))$$

[All operators defined on Wick monomials and extended by linearity + graph degree]

Two facts: $u \in \mathcal{V}$

① $m(u) = a^*(u) + a(u)$ [straight forward]

② $C * u \in \Omega$

$$(C * u)_k = \sum_e C_{k,e} * u_e \quad [\text{Malliavin...}]$$

and $\frac{\delta}{\delta(C * u)} = a(u)$

[check on Wick monomials]

Concrete operators:

$$\nabla_l := d\Gamma(\mathcal{Q}_l) \quad l=1, \dots, d$$

$$\Delta := \sum_{l=1}^d \nabla_l^2$$

$$\left. \begin{aligned} a_l^* &:= a^*(e_l) \\ a_l &:= a(e_l) \end{aligned} \right\} \left\{ \begin{aligned} e_l &\in V, (e_l)_j(x) = \delta_{lj} \delta(x) \\ l &= 1, \dots, d \end{aligned} \right.$$

$$\Delta^* = \Delta, \quad \nabla_l^* = -\nabla_l$$

$$\exp\{z \cdot \nabla\} =: T_z, \quad T_z f(\omega) = f(\tau_z \omega)$$

$$\exp\left\{\frac{1}{2} t \sigma^2 \Delta\right\} =: Q_t \quad \left[\begin{array}{l} \text{the unitary group of} \\ \text{translations} \end{array} \right.$$

$$(Q_t f)(\underline{\omega}) = \int_{\mathbb{R}^d} \frac{e^{-z^2/2\sigma^2 t}}{\sqrt{2\pi\sigma^2 t}} f(\tau_z \omega) dz$$

[the semigroup of BM in random scenery]

The infinitesimal generator,

$$\lim_{t \rightarrow 0} t^{-1} E \left(f(\eta(t)) - f(\eta(0)) \mid \eta(0) = \omega \right) = \left(\frac{\sigma^2}{2} \Delta + \sum_{l=1}^d m(e_l) \nabla_l + \frac{\delta}{\delta F} \right) f(\omega)$$

checked e.g. for

$$f(\omega) = : \phi(\nu_1) \dots \phi(\nu_n) :$$

with $\nu_1, \dots, \nu_n \in \mathcal{V}$,

sufficiently smooth

Note: $F = -C * h$

$$h \in \mathcal{V}, \quad h_l = \partial_l \delta$$

We get — using earlier identities

$$G = \frac{\sigma^2}{2} \Delta + \sum_{l=1}^d (a_l^* \nabla_l + \nabla_l a_l)$$

$$G^* = \frac{\sigma^2}{2} \Delta + \sum_{l=1}^d (a_l^* \nabla_l + \nabla_l a_l)$$

Yaglom reversibility:

$$G^* = J G J$$

$$\eta^*(t) := -\eta(-t), \quad \eta^*(\cdot) \stackrel{\text{law}}{=} \eta(\cdot)$$

Ergodicity:

$$\mathcal{D}(f) = - (f, Gf) = -\frac{\sigma^2}{2} (f, \Delta f)$$

$$\{ \mathcal{D}(f) = 0 \} \Leftrightarrow \{ f = \text{const} \}$$

Notation

$$S := -\frac{1}{2} (G + G^*) = -\frac{\sigma^2}{2} \Delta$$

$$A := \frac{1}{2} (G - G^*) = \sum_{l=1}^d (a_l^* \nabla_l + \nabla_l a_l) = A_+ + A_-$$

$$S: \mathcal{H}_n \rightarrow \mathcal{H}_n; \quad A_+: \mathcal{H}_n \rightarrow \mathcal{H}_{n+1}; \quad A_-: \mathcal{H}_n \rightarrow \mathcal{H}_{n-1}$$

$$S|_{\mathcal{X}_0} = 0; \quad A_+|_{\mathcal{X}_0} = 0; \quad A_-|_{\mathcal{X}_0 \oplus \mathcal{X}_1} = 0.$$